

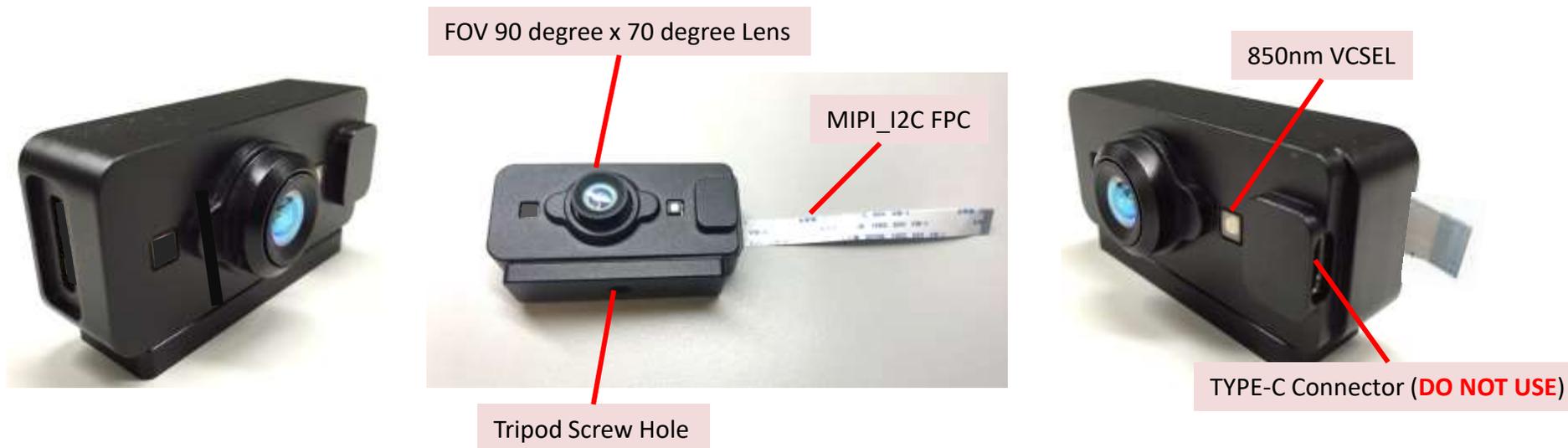
TOF V4T-Evaluation Module (EVM) Hardware Guide

17st Jun. 2019

Ver. 2.5

- **Introduction**
- **TOF module – Overview**
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 - Dimension of V4T-EVM
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- **Safety Instructions**

■ V4T Module – General Introduction



*** The visual appearance of the module may change due to different module suppliers**

V4T module is a 3D camera module using Panasonic's VGA ToF sensor P/N MN34906. This module can be used to build prototypes of 3D imaging solutions for short to middle range applications. With a small form-factor and light weight, it can be seamlessly integrated to robotics platform, consumer and portable solution prototypes.

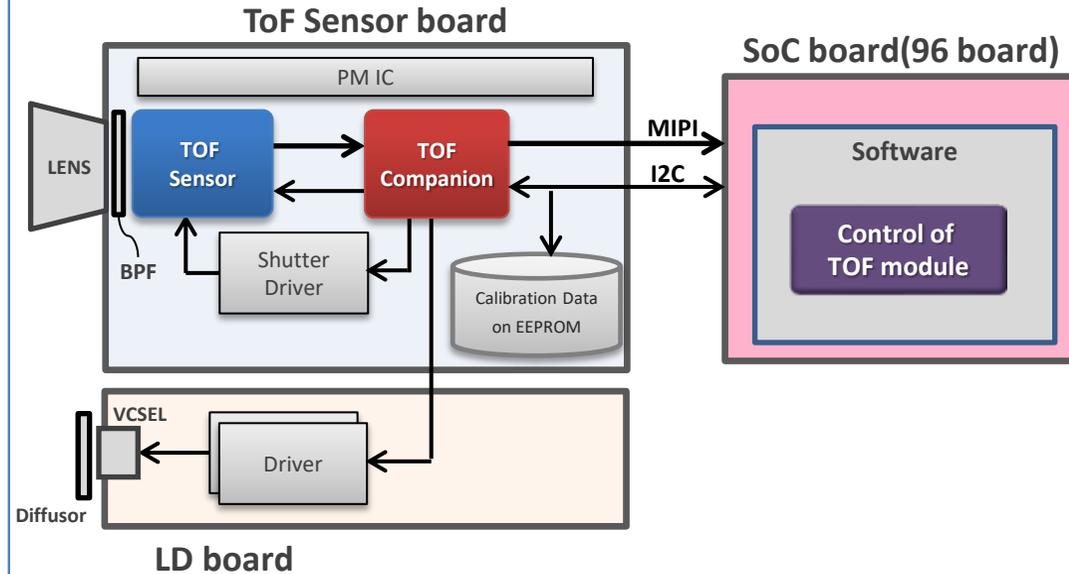
This V4T module provides about 1% depth error and 2% depth variation(standard deviation) of depth sensing from 0.2 m to 4.5 m range with 90 degree x 70 degree wide FOV, multiple signal output of depth, IR and background.

Although, this module is not designed for commercial production, yet it provides a preview of how a commercial 3D camera product using Panasonic's ToF sensor will look like.

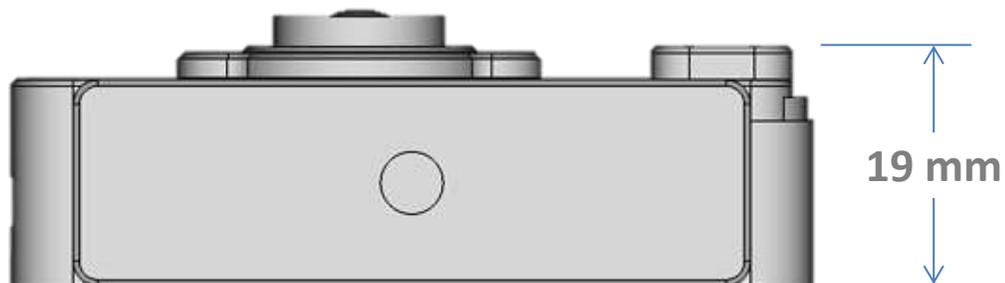
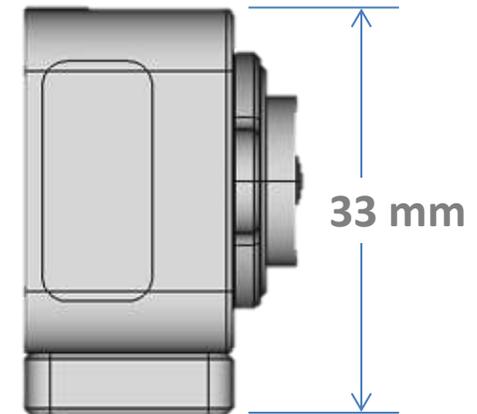
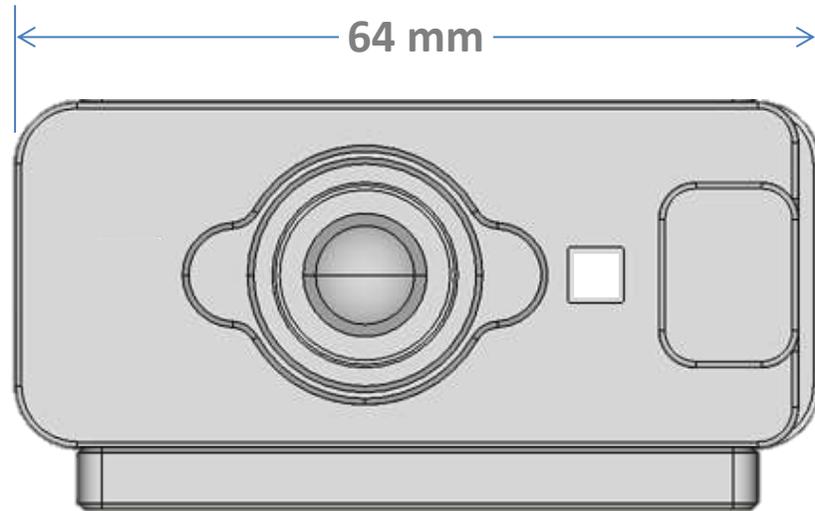
■ Specifications

Parameter	V4T-EVM – for in-door use		
TOF Sensor	1/4" VGA /IR – TOF		
Resolution	640 x 480 (VGA)		
Lens	FOV	H: 90° x V: 70°	
	Aperture	F1.2	
VCSEL	850nm x 1pc		
Performance	Mode 0:	Mode 1:	
	Short range	Long range	
	Camera Distance	0.2 to 1.2 [m]	0.5 to 4.5 [m]
	Frame Rate	30 fps	20 fps
Interface	MIPI (CSI-2) / I2C		
Module Size	64 x 33 x 19 [mm]		
Supply Voltage	DC 5V (From 4.85V to 5.3V)		
Operating Temperature	Ta= 0 to +60°C		

■ Block Diagram



Dimension of V4T EVM

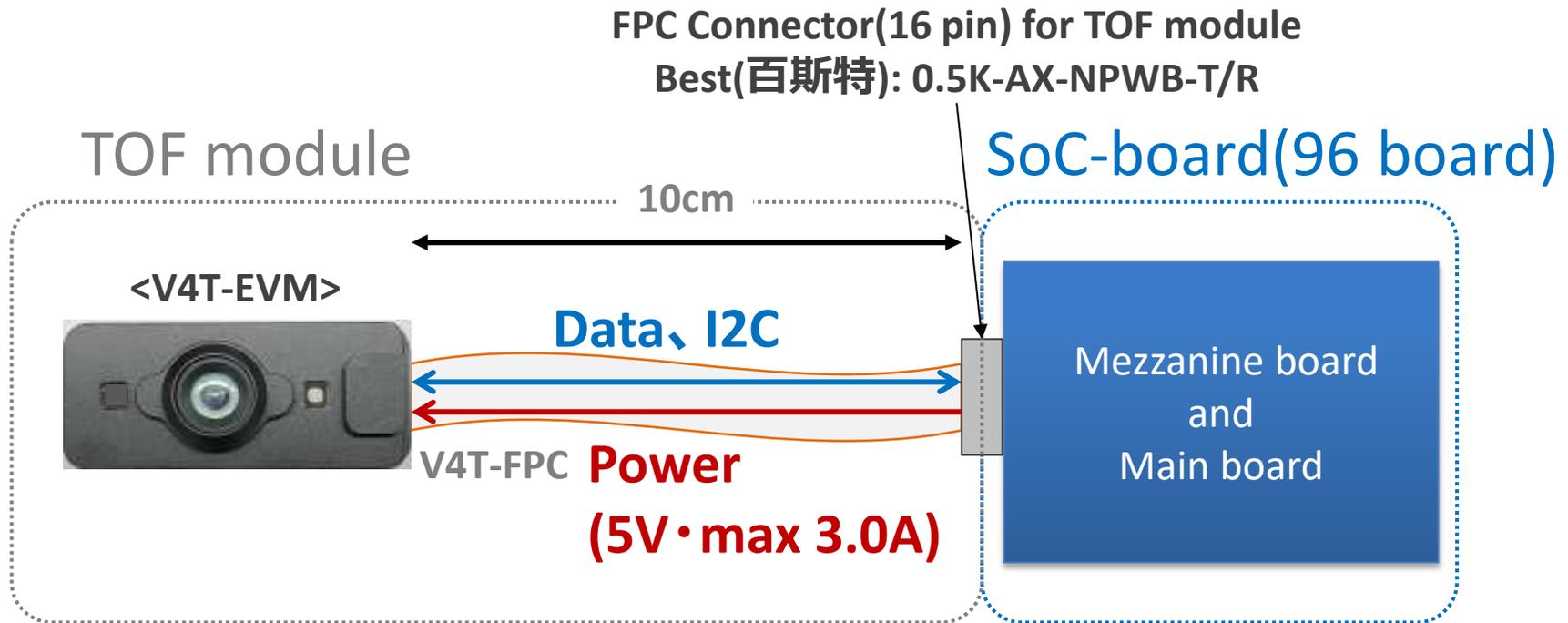


Dimension (mm)

W	64
D	19
H	33

* The visual appearance/size of the module may change due to different module suppliers

Connection of V4T EVM to SoC board

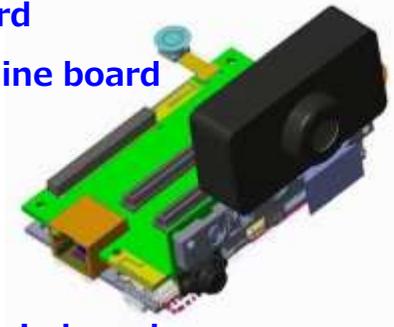


96-board

Mezzanine board

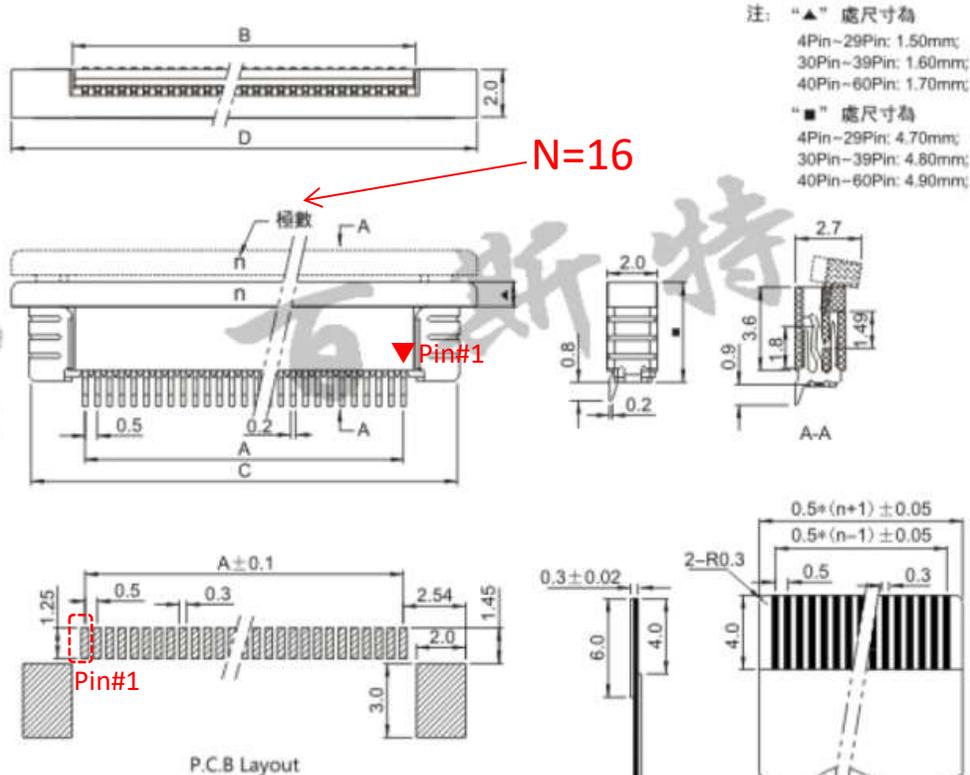
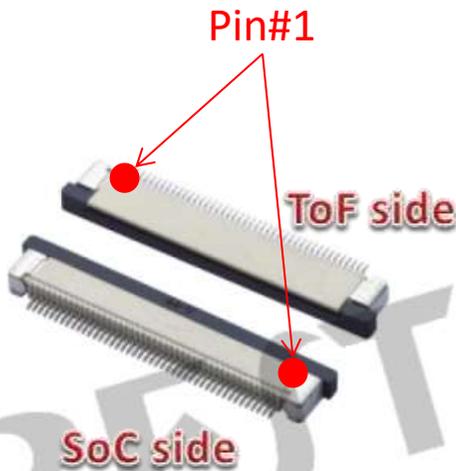
TOF module
V4T-EVM

Main board



FPC Connector Specs for V4T EVM

0.5K-AX-NPWB-T/R



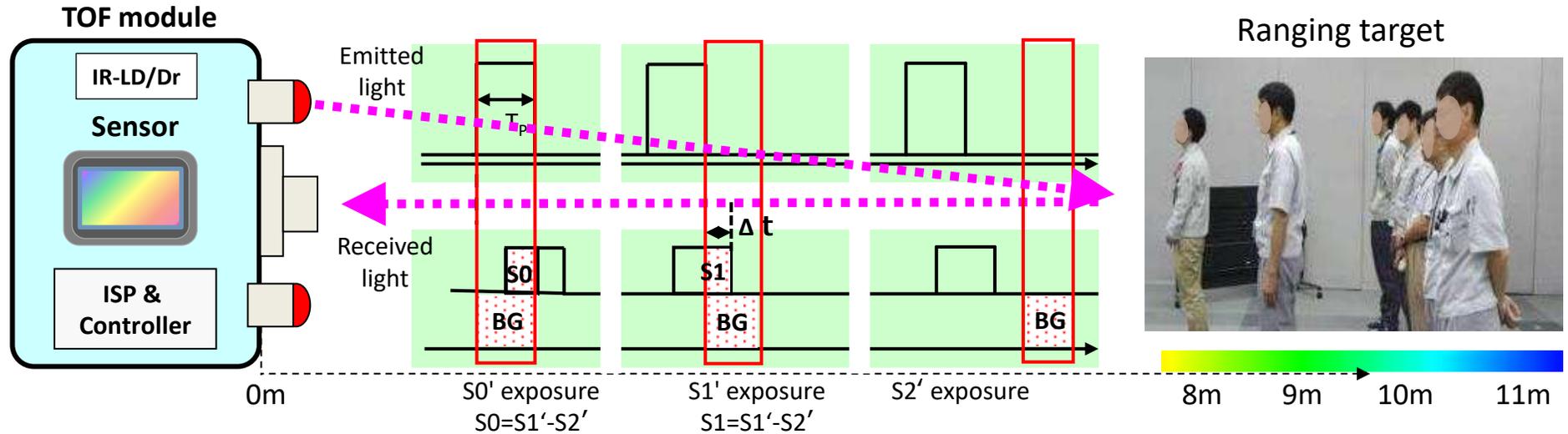
注：“▲”處尺寸為
 4Pin~29Pin: 1.50mm;
 30Pin~39Pin: 1.60mm;
 40Pin~60Pin: 1.70mm;
 “■”處尺寸為
 4Pin~29Pin: 4.70mm;
 30Pin~39Pin: 4.80mm;
 40Pin~60Pin: 4.90mm;

空位	A	B	C	D
4	1.50	2.60	8.35	7.85
5	2.00	3.10	8.85	8.15
6	2.50	3.60	9.35	8.65
7	3.00	4.10	9.85	9.15
8	3.50	4.60	10.35	9.65
9	4.00	5.10	10.85	10.15
10	4.50	5.60	11.35	10.65
11	5.00	6.10	11.85	11.15
12	5.50	6.60	12.35	11.65
13	6.00	7.10	12.85	12.15
14	6.50	7.60	13.35	12.65
15	7.00	8.10	13.85	13.15
16	7.50	8.60	14.35	13.65
17	8.00	9.10	14.85	14.15
18	8.50	9.60	15.35	14.65
19	9.00	10.10	15.85	15.15
20	9.50	10.60	16.35	15.65
21	10.00	11.10	16.85	16.15
22	10.50	11.60	17.35	16.65
23	11.00	12.10	17.85	17.15
24	11.50	12.60	18.35	17.65
25	12.00	13.10	18.85	18.15
26	12.50	13.60	19.35	18.65
27	13.00	14.10	19.85	19.15
28	13.50	14.60	20.35	19.65
29	14.00	15.10	20.85	20.15
30	14.50	15.60	21.35	20.65
31	15.00	16.10	21.85	21.15
32	15.50	16.60	22.35	21.65
33	16.00	17.10	22.85	22.15
34	16.50	17.60	23.35	22.65
35	17.00	18.10	23.85	23.15
36	17.50	18.60	24.35	23.65
37	18.00	19.10	24.85	24.15
38	18.50	19.60	25.35	24.65
39	19.00	20.10	25.85	25.15
40	19.50	20.60	26.35	25.65
41	20.00	21.10	26.85	26.15
42	20.50	21.60	27.35	26.65
43	21.00	22.10	27.85	27.15
44	21.50	22.60	28.35	27.65
45	22.00	23.10	28.85	28.15
46	22.50	23.60	29.35	28.65
47	23.00	24.10	29.85	29.15
48	23.50	24.60	30.35	29.65
49	24.00	25.10	30.85	30.15
50	24.50	25.60	31.35	30.65
51	25.00	26.10	31.85	31.15
52	25.50	26.60	32.35	31.65
53	26.00	27.10	32.85	32.15
54	26.50	27.60	33.35	32.65
55	27.00	28.10	33.85	33.15
56	27.50	28.60	34.35	33.65
57	28.00	29.10	34.85	34.15
58	28.50	29.60	35.35	34.65
59	29.00	30.10	35.85	35.15
60	29.50	30.60	36.35	35.65

空位	A	B	C	D
4	1.50	2.60	8.35	7.85
5	2.00	3.10	8.85	8.15
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7	3.00	4.10	9.85	9.15
8	3.50	4.60	10.35	9.65
9	4.00	5.10	10.85	10.15
10	4.50	5.60	11.35	10.65
11	5.00	6.10	11.85	11.15
12	5.50	6.60	12.35	11.65
13	6.00	7.10	12.85	12.15
14	6.50	7.60	13.35	12.65
15	7.00	8.10	13.85	13.15
16	7.50	8.60	14.35	13.65
17	8.00	9.10	14.85	14.15
18	8.50	9.60	15.35	14.65
19	9.00	10.10	15.85	15.15

Principle of Time of Flight

The distance measuring principle for V4T-EVM is based on the Time of Flight concept as shown in the figure below:



Sensor Output (RAW)

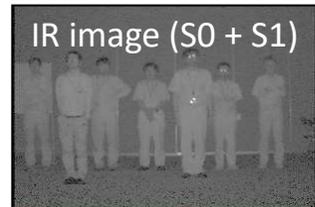
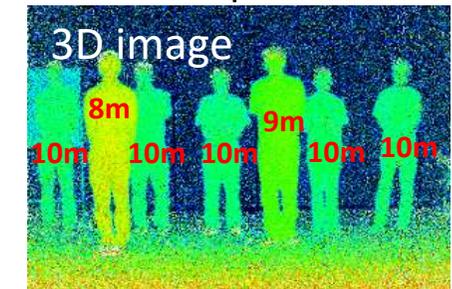


Depth Calculation

$$Z = C \times \frac{\Delta t}{2} = \frac{C \cdot T_p}{2} \times \left(\frac{S1}{S0 + S1} \right)$$

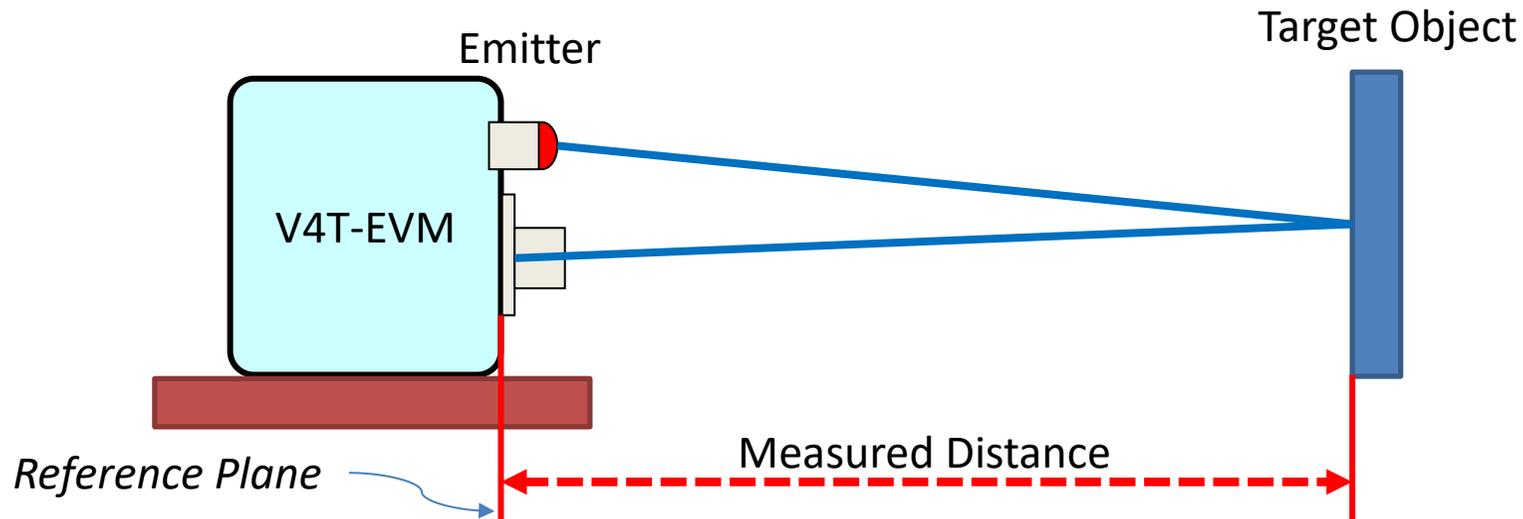
Δt : Time of Flight
 C : Light speed
 T_p : IR pulse width

Camera Output



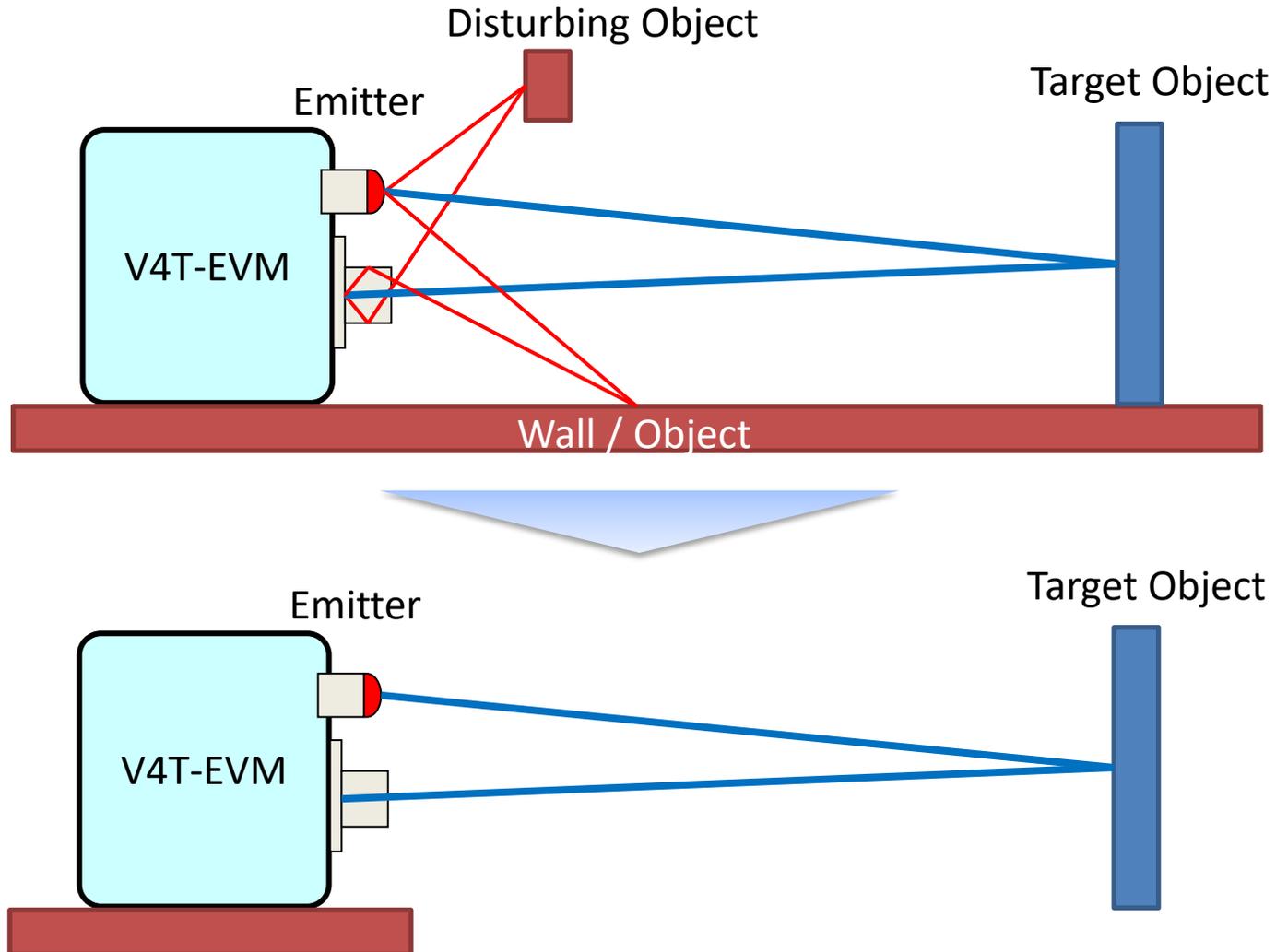
Reference Plane:

- The front edge of module has been used as the reference plane for calibration of V4T-EVM, so all measurements taken by V4T-EVM are values of distance (in mm) from this front edge. Refer to the figure below:



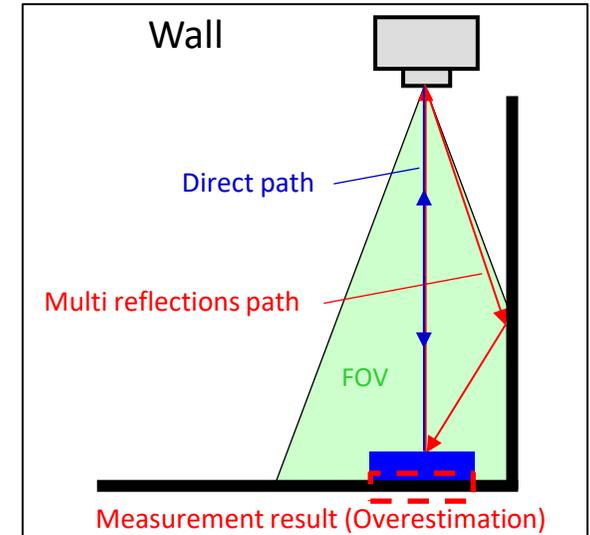
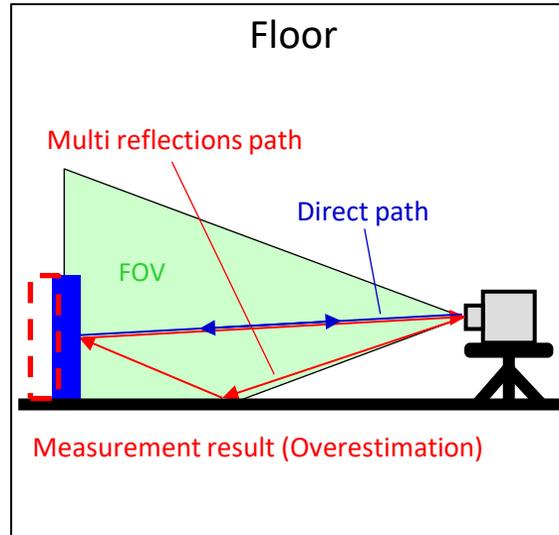
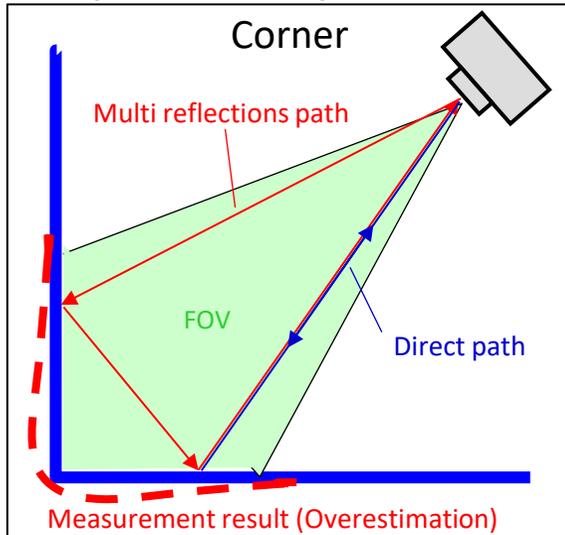
Light Scattering

Light scattering occurs due to unwanted reflections within the optics. This cannot be eliminated completely. In order to avoid scattered light issue as much as possible, V4T-EVM should be placed at the greatest distance possible from disturbing object from which light might be reflected.



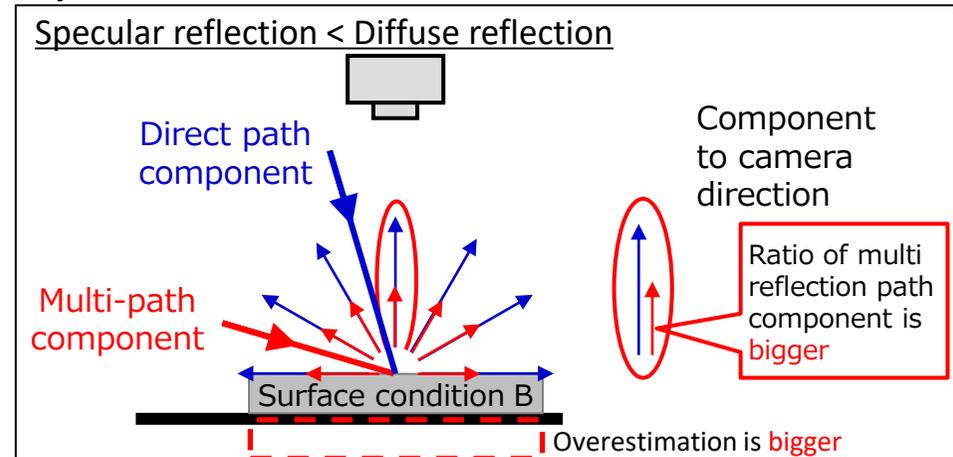
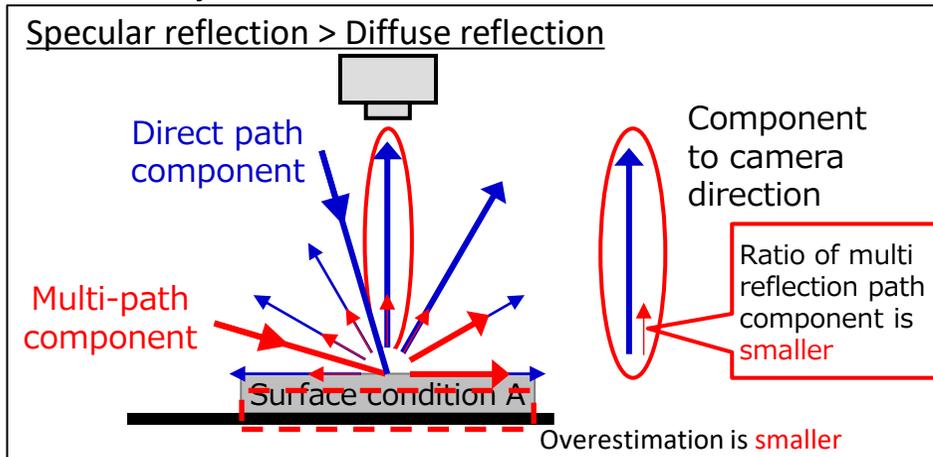
Multipath Interference

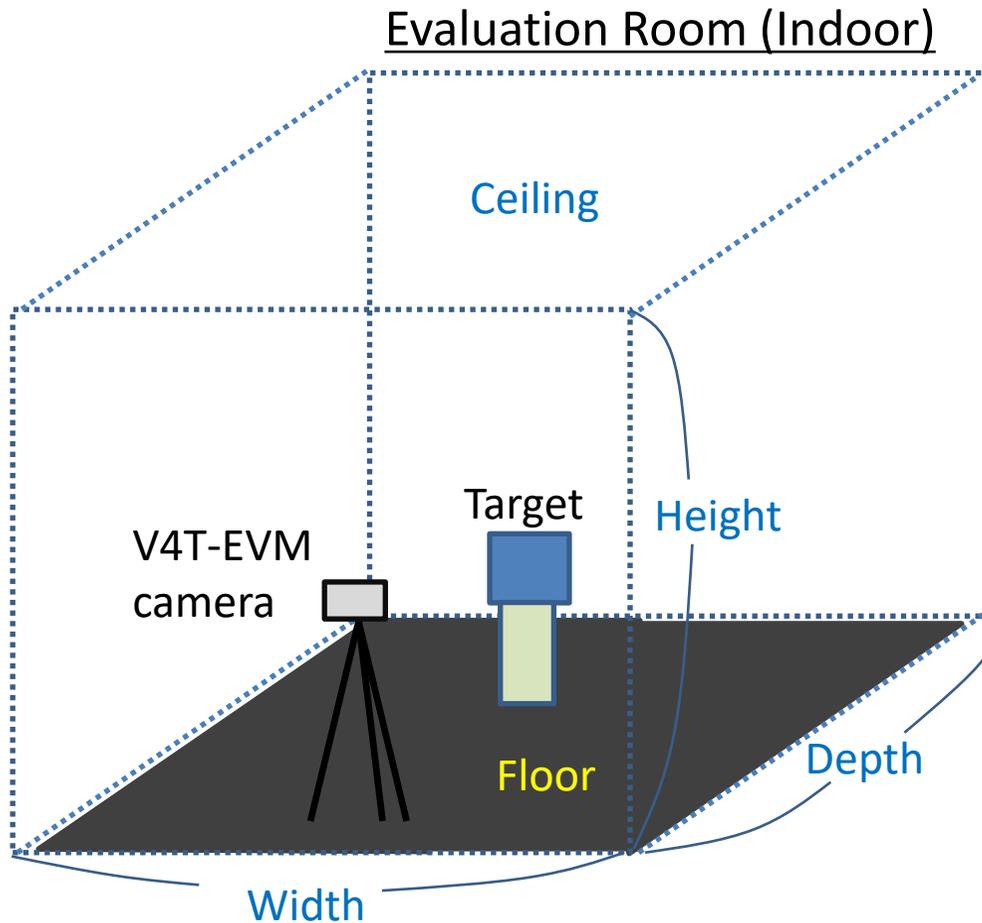
1) Example of Multipath Interference



2) Dependency on surface condition of the measured object

Influence level of the multi-path reflection depends on not only the reflectance of the multi-path objects and measured object but also the surface condition of the measured object.

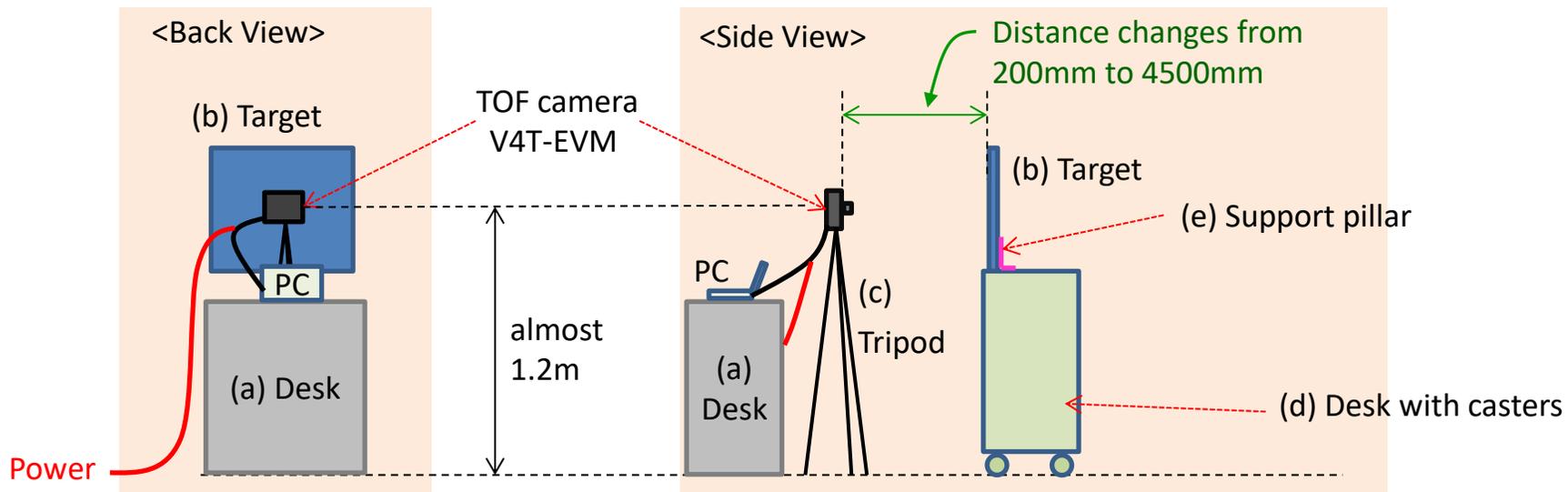




Part	Description
Ceiling	Fluorescent light only
Width	9m or over
Depth	6m or over
Height	3.5m or over
Floor	Black (or low reflectance) rug *

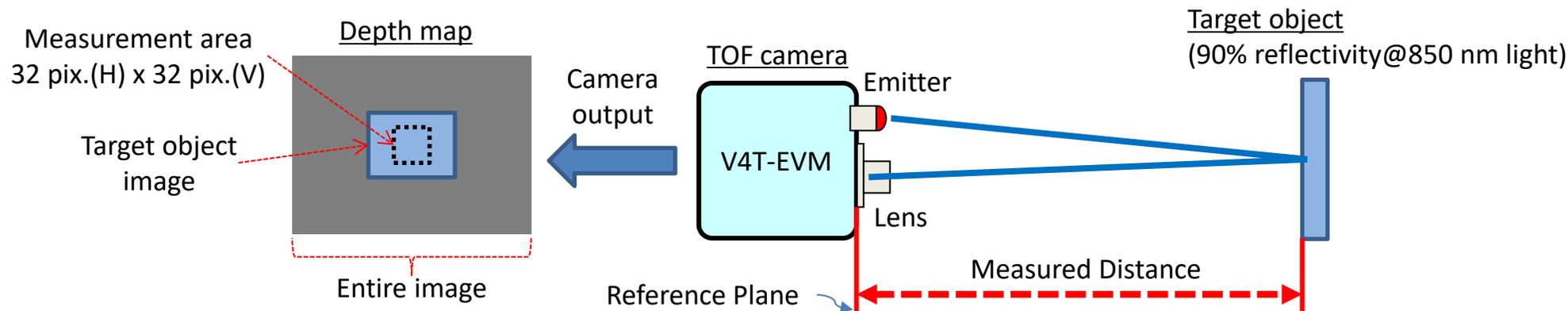
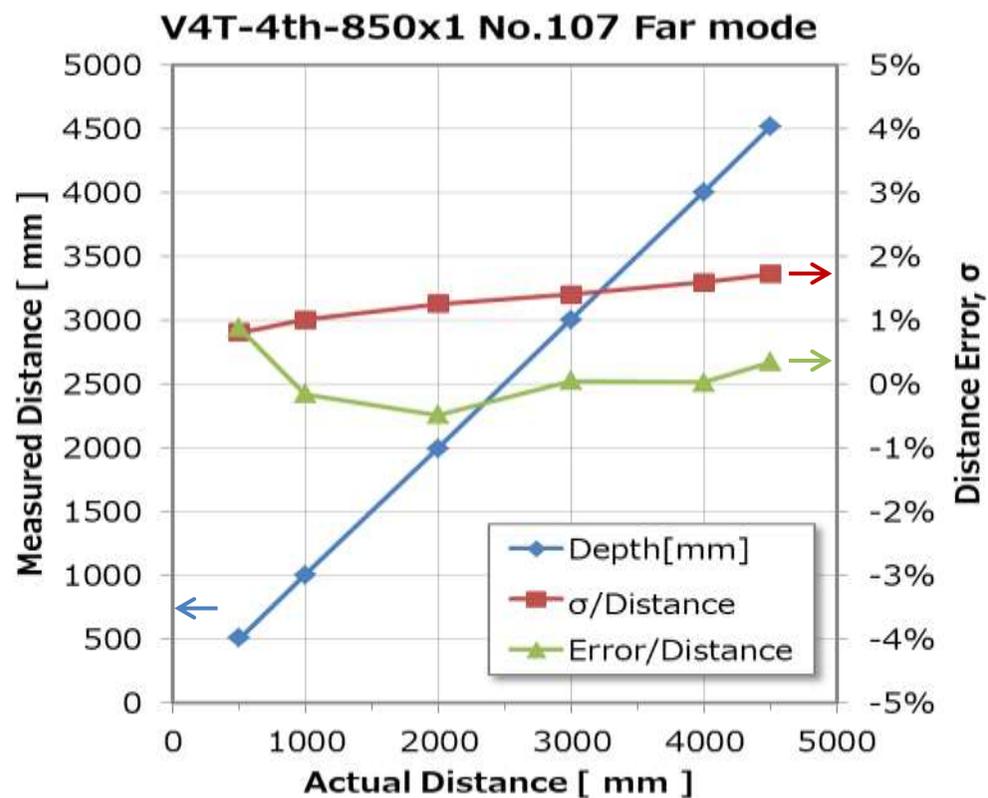
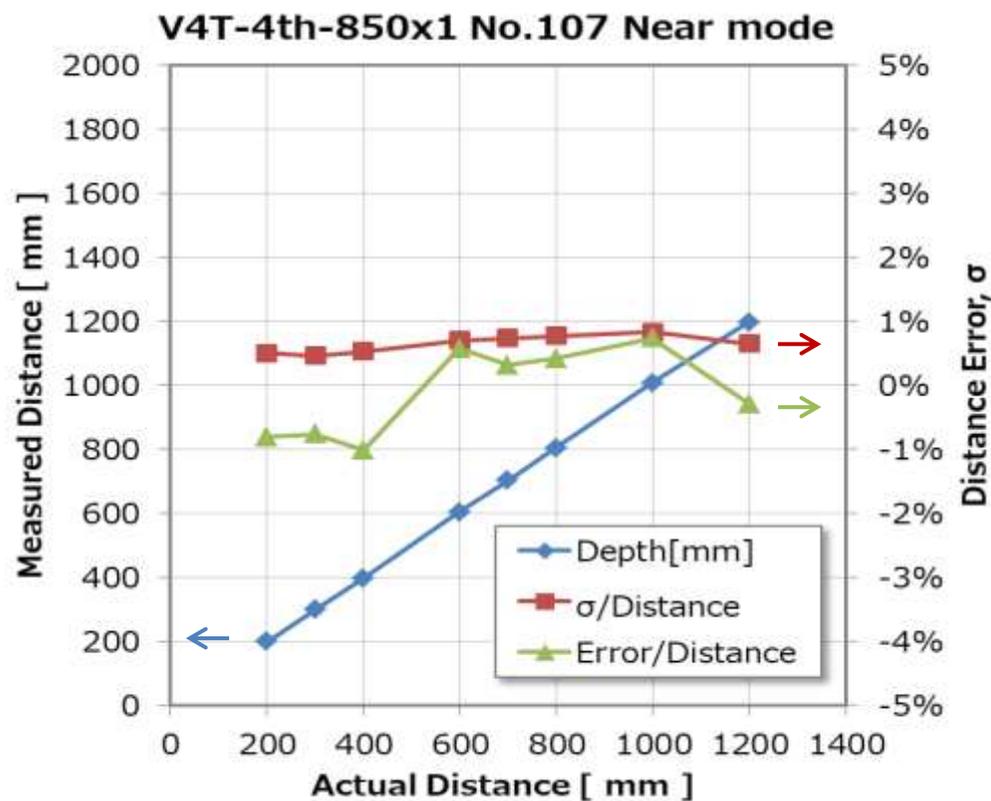
* It is important to reduce the reflectivity of the floor to avoid multipath interference.

Evaluation equipment



No	Items	Detail specs
(a)	Desk	Normal PC desk.
(b)	Target	<ul style="list-style-type: none"> - Flat, thin and durable board - Target size is 60 cm (H) x 50 cm(V) - Reflectivity is 90%@850 nm light
(c)	Tripod for camera	Height should be adjusted to around 1.2m.
(d)	Desk with caster	Desk with casters is useful to change the distance between the target and the TOF camera.
(e)	Support pillar	Book stand etc.

Examples of Depth Evaluation Results



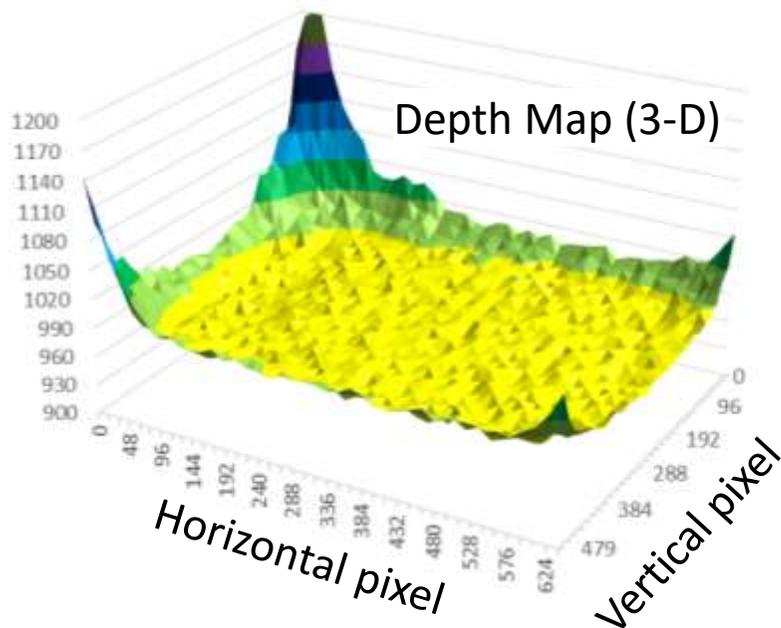
Corners of depth map has large depth error

[Phenomena]

Due to small mismatch between lens FOV and diffuser FOI of light source in the current TOF module, depth at image corners has large error as shown in the following depth map example.

Please be aware this characteristics when using the current ToF module.

[Example of Depth Map]

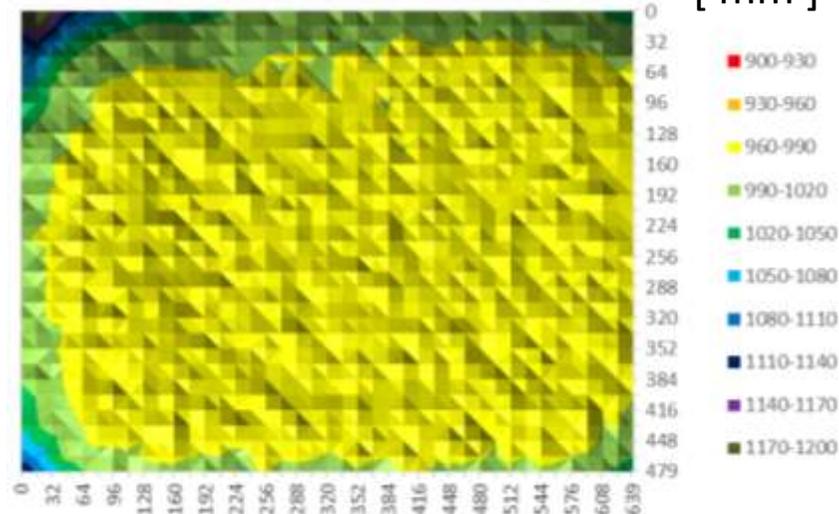


[mm]



Depth Map

[mm]



Horizontal pixel

Please observe the following condition for the safety operation of V4T-EVM.

- In any case, it is **not** allowed to open V4T-EVM or to make any changes to the hardware.
- Only the power supply provided by Thundercomm's 96-board is allowed to be used with the camera.
Do not use other power supply.
- V4T-EVM is **not** waterproof and dustproof. Do **not** use under rain.
- Do **not** apply any register settings and EEPROM values in V4T-EVM (especially laser emission settings)
- Handle with care for V4T-EVM or power supply connector.
- Do **not** touch Diffuser or Lens.
- V4T-EVM is **not** certified for any safety related applications.

By using V4T-EVM, the user agrees to indemnify Panasonic against any loss (material, non-material or others). Under no circumstances Panasonic takes any responsibility or liability.

The modules must be used strictly satisfying above guidelines. Any claims for replacement of modules will be by the sole discretion of module supplier.